



1. Log in

- 2. Create a new folder in My Documents (=H:\[Your DaVisProjectsName])
- 3. Transfer data from <u>\\soton\ude\courses\SESG6031</u> to My Documents (=H:\[Your DaVisProjectsName]) <u>including *.exp files</u>
 - DIC_disc_tutorial
 - DIC_Dog_bone

ame	Date modified	Туре	Size
Camera_setup	28/03/2014 16:21	File folder	
DIC_bmp	11/04/2013 12:41	File folder	
DIC_disc	28/03/2014 16:22	File folder	
DIC_disc_tutorial	28/03/2014 16:21	File folder	
DIC_Dog_bone	28/03/2014 16:22	File folder	
GRID_Disc	28/03/2014 16:22	File folder	
SG_Ext_Dog_bone	28/03/2014 16:22	File folder	
TSA_Disc	28/03/2014 16:22	File folder	
TSA_Dog_bone	28/03/2014 16:22	File folder	

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- 4. The address of the software licence server is 192.168.168.174
- 5. You may need to search for the licence
- 6. The licence file you will need when you install the DaVis software on your own machine is here: <u>\\soton\ude\Courses\SESG6031\Software\Davis</u>





LaVision Imaging Systems

LAVISION

FOCUS ON OPTICAL MEASUREMENT SOLUTIONS



Fluid Mechanics Advanced Flow Field Imaging PIV, PTV, LDV



Combustion Species, Temperature, Soot (Laser) Imaging in Flames



Scalar Flow Imaging LIF, Rayleigh, BOS



Automotive Engine, Aerodynamics, Testing Engine Diagnostics, PIV, DIC Fluid-Structure Interaction Aeroelasticity, Hydroelasticity DIC + PIV



Sprays Spray Analysis, Quality Control (Laser) Imaging in Sprays, PDI



Materials Testing Surface,(Volume) Deformation, Strain DIC, DVC



Particle Characterization Size, Shape, Velocity Shadowgraphy, IMI

The Digital Image Correlation process





The Digital Image Correlation process





DIC gives full field Displacement and Strain









Imaging set-up Calibration Recording

Background / Reminder from the Lab



• Normally easiest to optimise the imaging set-up by viewing the sample first (then calibrate later)

	Reminders regarding the set up:
Processing after Take/Grab	 Orientate sensor with sample (fill the image with the sample)
C.AOI 1 AOI 2 AOI 3	Position the camera(s) correctly
ihow overlays AOI rectangles	 Optimise the lighting (avoid reflections)
focus quality	 Exposure time, lighting, f#
Show overlay	 Focussing



Compute

Accurate 2D DIC requires:

- Planar sample
- Camera is perpendicular to sample surface OR a 2D calibration

White Light Source

Negligible displacement in z direction (z movement = artificial strain)

Typically appropriate to use where sample is loaded to small strain magnitudes (<10%) in tensile test machines









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Note that in windows explorer, a project consists of:

- A folder containing the images, calculated data, etc
- A *.exp file which defines the project
- You need the folder and the *.exp file when moving a project from one PC to another

(c)	Workspaces		
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Strain



- Seed points provide the predictor as to where adjacent subsets should search
- Adjacent cells then provide prediction regarding likely
 displacement and inform their neighbours where to search



When should I define seed point locations?



- Region grow stops at boundary of sample
- If the sample has more than one zone, or separated parts, then you should ensure that at least one seed point exists per zone
- The matching (region grow) evolves from each seed point





• Lower accuracy (due to error summing) but a safer calculation mode

Differential : 1224466

- > Use this mode only when you need to know displacement relative to previous image
- Normally only used for granular flows





- discontinuities (e.g. Cracks).
- decreasing step size (oversampling), can be helpful if applying the smoothing filter – see later
- Typical step size = 0.3*[subset size] = 10 pix



Calculate Displacements (5) – calculation scheme









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• Activate the info bar by clicking small triangle (Load, time,...)







• Banding visible between 0.2% and 1% Strain

Peak locking due to systematic error with bilinear image interpolation scheme











Processing : Polynomial (and other) smoothing







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for DIC processing

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Sequence SIdAvgGs_2D_L=12

Processin Processin Plot

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image sequence below the original images

These images could then become the input

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K < 4 > > > 0 (7) Maximum, Carrent 1 2 + 1 2 Range 1 2 - 29



